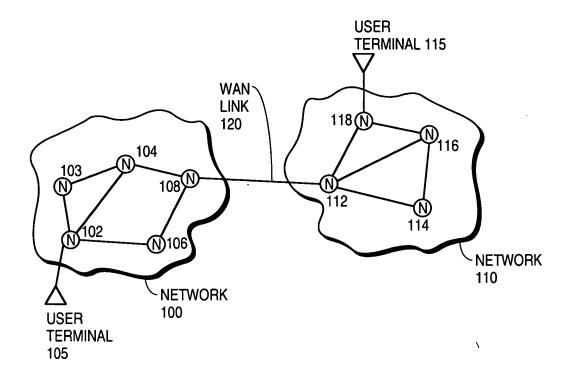
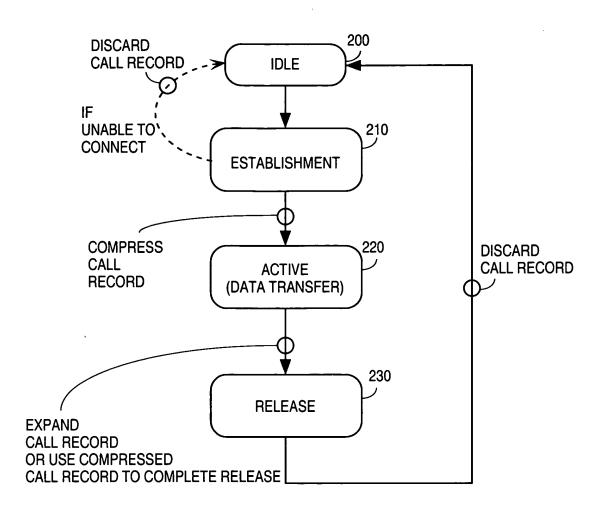
i



N=NODE

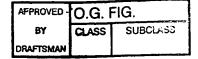
Fig. 1 (Prior Art)

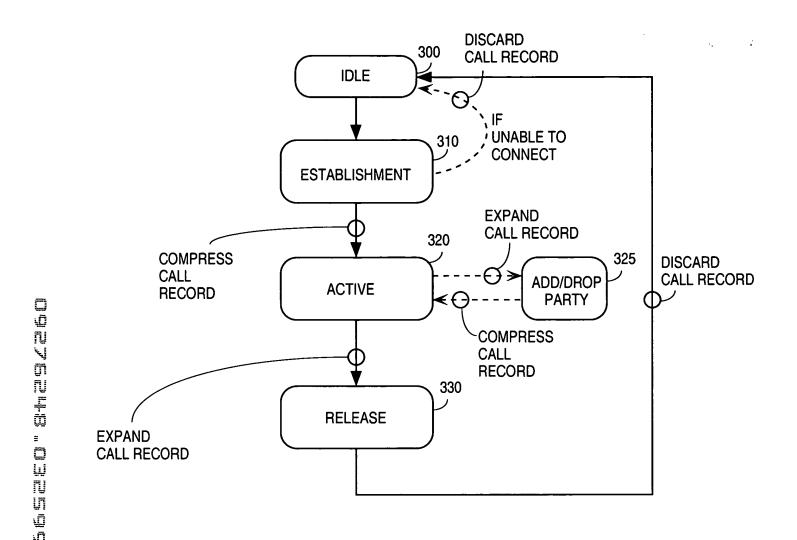
2.



POINT-TO-POINT CALL

Fig. 2





POINT-TO-MULTI-POINT CALL

Fig. 3

14.)



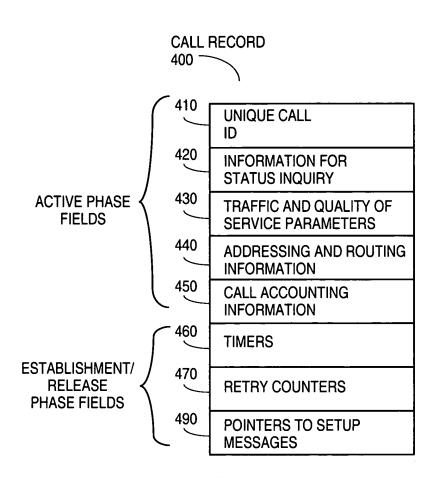


Fig. 4

ÁPPROVED 1	O.G. FIG.	
BY	CLASS	SUECLA:
DRAFTSMAN		

DORYGRAG DEST

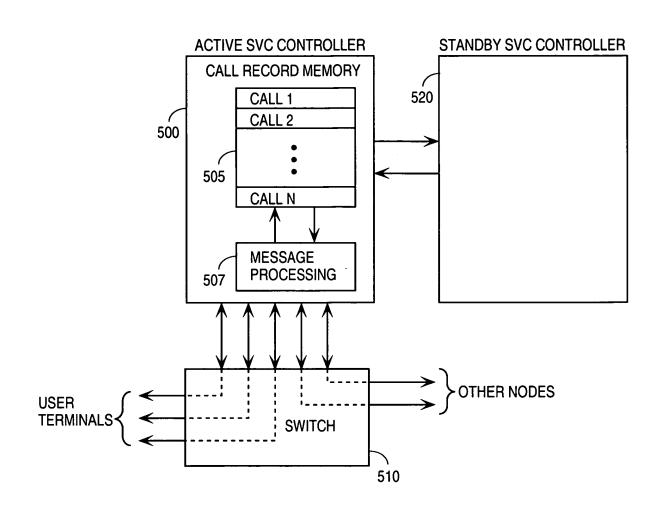


Fig. 5